### EM-217B (-H) INVERTER FOR 230VAC 1-ph INDUCTION MOTORS

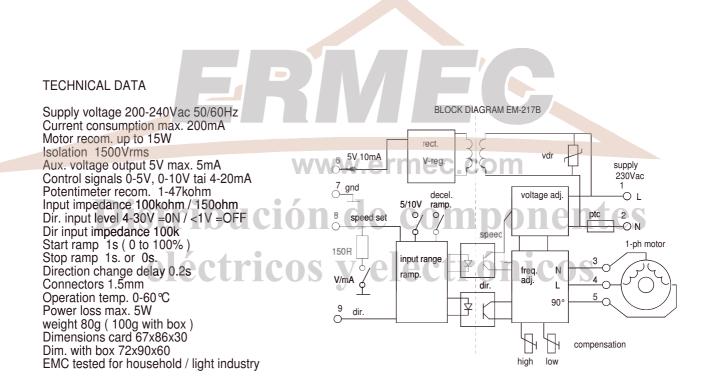




#### **FEATURES**

- -speed control
- -direction change
- -start ramp
- -slip compensation
- -isolated control
- -V/mA control signal
- -EM-217B open card
- -EM-217B-H (housed)
- -low disturbances

EM-217B is a frequency inverter for speed control of small 1ph induction motors. This device creates two output voltages with 90 deg. phase difference to each other, so theres no need for auxiliary capasitor like often with 1ph motors. The frequency output range is from 15Hz up to 80Hz. The output stage works with PAM princible and that way the EMC emissions are very low. The control can be done with voltage or mA signal or with potentiometer. The rotation direction can be changed with digital command. All control inputs are galvanically isolated from mains supply. Device has also a start and stop ramp for smooth operation. If needed, the stop ramp can be disabled for quicker stop. The EM-217B has self recovery mains fuse that offers a good immunity against the mains voltage spikes





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#### **INSTALLATION**

-Supply voltage 200-240Vac 50/60Hz

-Supply must be switched off when connecting

-Settings of switches: input range: V / mA / Potentimeter

stop ramp on / off -Turn compensation trims to recommended position (if motor is unknown, set both trims to min. position)

#### NOTICE!

- Installation of this device is allowed only for person who has competence for mains voltage voltage installation like a licensed electrician.

- The slip compensation adjustments are on mains voltage side. So use allways insulated tools.

#### INTRODUCTION

Turn supply on and start to increase speed set voltage. Motor should start to run smoothly from low speed to high speed.

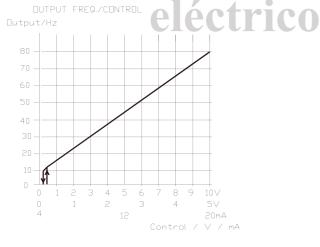
Try to change direction when motor is running at high speed. Motor should slow down and start to the other direction. If a fast direction change is desired, change the "stop ramp" link to off position.

Adjustment of the compensation:

Turn "high" trim to middle position and "low" trim to minimum position. Set the motor to run at low speed and adjust "low" trim slowly towards max. until motor speed starts to rise. Then load the motor gradually and you should notice the driver increasing the motor speed. The compensation increase on higher speeds can now be adjusted with the "high" trim.

# In this example device is controlled with voltage signal and logic signal. Notice! input range is selected with links In example beneath the device is controlled with switch and potentiometer potentiometer Height 30mm $\bigcirc$ LETHAL VOLTAGE 230VAC

## Distribució



Example: rotation speed range calculation 4-pol. motor 1500rpm/50Hz given slip on nominal load 300rpm 1ph PANASONIC 4P6WS1

recommended settings