Proportional, industrial hand grip controllers • non-contacting Hall effect technology



351,402,008

DISTINCTIVE FEATURES

SIL 2 compatible - Redundant Hall sensors Resists high axial load (1780 N - 400 lbf) Shallow mounting depth of <60 mm (2.36) Rated for 10 million lifecycles **SAE CAN bus J1939-71**



ENVIRONMENTAL SPECIFICATIONS

- Operating Temperature: -40 °C to +85 °C (-40 °F to +185 °F)
- Storage Temperature: -40 °C to +85 °C (-40 °F to +185 °F)
- Above Panel Sealing: Up to IP67 (subject to handle configuration)
- Humidity: IEC 60068-2-38
- Thermal shock: SAE J1455 section 4.1.3.2
- Salt spray: IEC 60068-2-11
- Random vibration: IEC 60068-2-64
- Sinusoidal vibration: IEC 60068-2-6
- EMC Emissions:
- Radiated Emissions Level: ECE/324/Add.9:2012; CISPR 25:2002
- Radiated Emissions Level: CISPR 25:2008
- EMC Immunity:
- ESD: ISC 10605:2008; criteria A
- Radiated immunity: ISO 11452-2:2004; criteria B
- Bulk current injection immunity: ISO 11452-4:201; criteria A
- Pulse 1, Pulse 2a, Pulse 2b, Pulse 3a, Pulse 3b, Pulse 4, Pulse 5a: ISO 7637-2:2011; criteria A



C/ Francesc Teixidó, 22 P. E. Granland, Badalona Sur 08918 Badalona Barcelona (SPAIN)



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ELECTRICAL SPECIFICATIONS

- Technology: Redundant Hall effect sensor
- Supply voltage range: 7 35 VDC
- Typical current consumption: 12 V @ 53 mA
- Transient overvoltage max: 40 V
- Reverse polarity Max: -1000 VDC
- Output signal: SAE CANbus J1939-71
- Connections: Deutsch DTM04-6p



ELECTRICAL CONNECTIONS

- Six position connector: Deutsch DTM04-6P
- Wire: 22 AWG, PTFE insulation with expandable sleeve
- Length: 6:00" +/- 0.5" (bottom of joystick to connector)



MECHANICAL SPECIFICATIONS

- Operation: Two axis
- Deflection angle in X & Y directions:
- ±20° for square limiter plate (standard)
- ±16° for round limiter plate
- Operating torque, breakout: 1.28Nm*
- Operating torque, 50% travel: 1.93Nm*
- Operating torque, 100% travel: 3.21Nm*
- Maximum axial load: 400 lbf.
- Expected life: 10 million lifecycles (X and Y axis)
- Lever Action (centering): Spring return

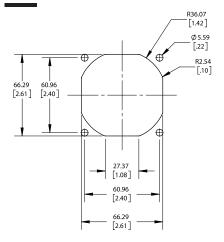


MATERIALS

- Shaft: Stainless steel
- Boot: Silicone
- Handles: Glass filled nylon
- Bezel: Hard black anodized aluminum
- Body: Aluminum
- Cover: Zinc plated steel
- Weight: 800 g
- *Considering most common options selected:
- Option M (1.24Nm)
- Option G (with guided feel)



PANEL CUT-OUT





CAN J1939 INTERFACE SPECIFICATION

The XD Series utilizes redundant Hall effect sensors to measure the primary X and Y axis. The CAN controller support various button configurations as well as proportional thumbwheels and mini-joysticks for additional axis data.

All axis and button data are delivered on a CAN 2.0B compliant physical interface. Two additional signals allow configuration of the controller Source Address. Controller messages are delivered per the SAE J1939-71 message protocol.

CAN 2.0B INTERFACE PARAMETERS

- Baud rate: 250 Kbps
- Transmission repetition rate: 50 ms to 80 ms **
- BJMI/EJMI interval time: 20 ms
- Terminating resistor: No (available by special request to factory)
- Connection to Deutsch DTM04-6P connector:

Pin	Color	Function		
1	White	CAN Lo		
2	Green	CAN Hi		
3	Blue	Source Address SEL 1		
4	Orange	Source Address SEL 0		
5	Black	Ground		
6	Red	6 - 35 VDC		

^{**} Transmission repetition rate is dependent upon the faceplate configuration.

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CAN J1939 INTERFACE SPECIFICATION (CONTINUED)

CAN MESSAGE PROTOCOL

- Primary Axis and button data on Basic Joystick Message 1 (BJM1):
- Priority: 3
- Base PGN: 0xFDD6
- Source address: 0x101
- Data field: 8 bytes
- Redundant Axis data on Extended Joystick Message 1 (EJMI):
- Priority: 3
- Base PGN: 0xFDD7
- Source address: 0x101
- Data field: 8 bytes
- · Additional thumbwheels and mini-joysticks data on Extended Joystick Message 2 (EJM2):
- Priority: 3
- Base PGN: 0xFDD9 - Source address: 0x101
- Data field: 8 bytes

Note 1: Alternate source addresses can be configured by grounding of the blue and/or orange wires.

- Source address= Ox10: ORANGE= floating , BLUE= floating (default)
- Source address= Ox20: ORANGE= floating, BLUE= grounded Source address= Ox30: ORANGE= grounded, BLUE= floating
- Source address= Ox40: ORANGE= grounded, BLUE= grounded

BJM1 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	Primary X-axis neutral position status
1/3	2	Primary X-axis left position status
1/5	2	Primary X-axis right position status
1/7 to 2/8	10	Primary X-axis position data
3/1	2	Primary Y-axis neutral position status
3/3	2	Primary Y-axis down position status
3/5	2	Primary Y-axis up position status
3/7 to 4/8	10	Primary Y-axis position data
6/1	2	Button 4 status
6/3	2	Button 3 status
6/5	2	Button 2 status
6/7	2	Button 1 status
7/1	2	Button 8 status
7/3	2	Button 7 status
7/5	2	Button 6 status
7/7	2	Button 5 status
8/5	2	Button 10 status
8/7	2	Button 9 status

Note: If faceplate configured with n buttons, Trigger and/or paddle would be respectively positioned in Button n+1 and Button n+2.

EJM1 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	Redundant X-axis neutral position status
1/3	2	Redundant X-axis left position status
1/5	2	Redundant X-axis right position status
1/7 to 2/8	10	Redundant X-axis position data
3/1	2	Redundant Y-axis neutral position status
3/3	2	Redundant Y-axis down position status
3/5	2	Redundant Y-axis up position status
3/7 to 4/8	10	Redundant Y-axis position data

EJM2 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION		
1/1	2	A-axis neutral position status		
1/3	2	A-axis left position status		
1/5	2	A-axis right position status		
1/7 to 2/8	10	A-axis position data		
3/1	2	B-axis neutral position status		
3/3	2	B-axis left position status		
3/5	2	B-axis right position status		
3/7 to 4/8	10	B-axis position data		
5/1	2	C-axis neutral position status		
5/3	2	C-axis left position status		
5/5	2	C-axis right position status		
5/7 to 6/8	10	C-axis position data		



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CANOPEN INTERFACE SPECIFICATION

CANOPEN INTERFACE PARAMETERS
Baud rate: 250 kbits/s
Node ID: 20h
• Buttons: 1A0h (180h + Node ID)
Analog (axis) outputs: 2A0h (280h + Node ID)
• Heartbeat (500ms): 720h (700h + Node ID)
Axis resolution: 8-bit
Network Management: Auto start enabled

BUTTON OUTPUT CONFIGURATION

Button status is transmitted in the 8-byte data field of frames with an identifier of 1A0 (default).

IDENTIFIER	BYTE 0	BYTE 1	BYTE 2	BYTE 3	BYTE 4	BYTE 5	BYTE 6	BYTE 7
1A0	Buttons (7:0)	Buttons (15:8)	-	-	-	-	-	-

ANALOG OUTPUT CONFIGURATION

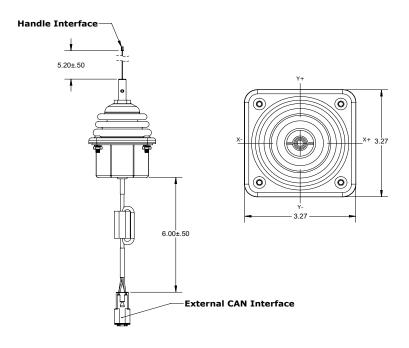
8-bit analog data is transmitted in the 8-byte data field of frames with an identifier of 2A0 (default).

IDENTIFIER	BYTE 0	BYTE 1	BYTE 2	BYTE 3	BYTE 4	BYTE 5	BYTE 6	BYTE 7
2A0	A_IN0(7:0)	A_IN1(7:0)	A_IN2(7:0)	A_IN3(7:0)	A_IN4(7:0)	A_IN5(7:0)	-	-



ELECTRICAL INTERFACE AND CONNECTIONS

DIMENSIONS





ERMEC, S.L. C/ Francesc Teixidó, 22 P. E. Granland, Badalona Sur 08918 Badalona Barcelona (SPAIN)

Tel. (+34) 902 450 160 Fax (+34) 902 433 088 ermec@ermec.com www.ermec.com

A PEM

XD series

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HANDLE INTERFACE



SERIAL LINK MOLEX 5013300400 CONNECTOR PIN# DESIGNATION

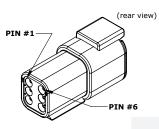
IF UART interface: 19200 baud, no parity, 8 bit, 1 stop bit, no hardware flow control

FUNCTION
Vcc (+5 V)
Rx
Tx
Ground

IF CAN interface:

PIN#	FUNCTION
1	Vcc (+5 V)
2	Rx
3	Tx
4	Ground

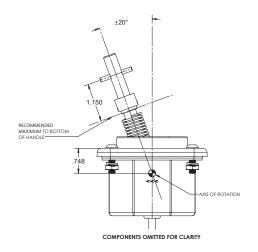
EXTERNAL CAN

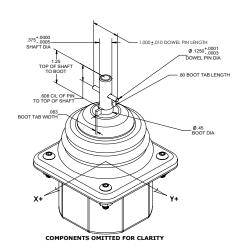


DEUTSCH DTM04-6P CONNECTOR PIN# DESIGNATION

PIN#	FUNCTION
1	CAN-LO
2	CAN-HI
3	SEL 1
4	SEL 2
5	Ground
6	Vin

MECHANICAL INTERFACE AND DIMENSIONS

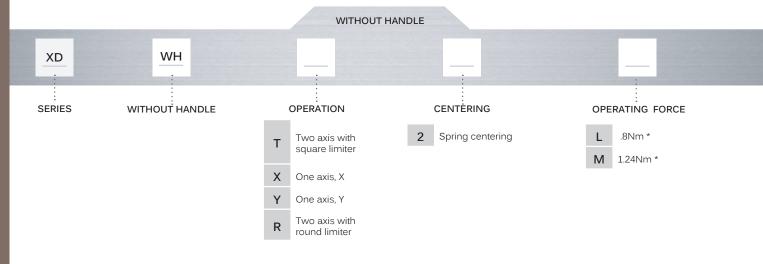


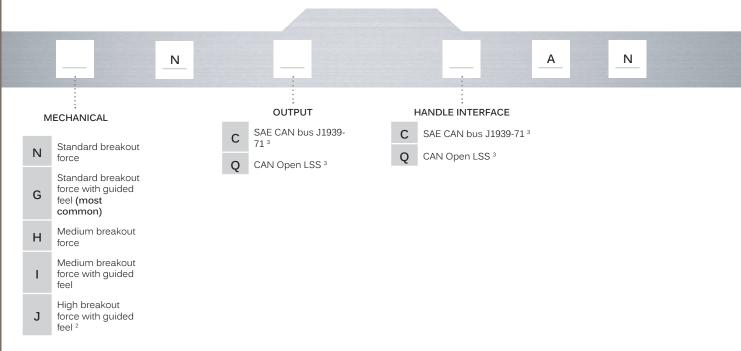


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BUILD YOUR PART NUMBER





The Guided feel option aids the joystick lever into the cardinal direction Guided feel option is recommended for «Operating force Option M»

- ¹ Measured at ±10° (50% travel) from center (without guided feel.)
- ² High breakout force can only come with round limiter plate.
 ³ Option selected for HANDLE INTERFACE must be the same as OUTPUT option.



ERMEC BCN

C/ Francesc Teixidó, 22 P.E. Granland, Badalona Sur 08918 Badalona (Barcelona) SPAIN

comercial@ermec.com Tel. (+34) 934 501 600 Fax (+34) 934 330 885 www.ermec.com

Tel. (+34) 918 285 651 madrid@ermec.com

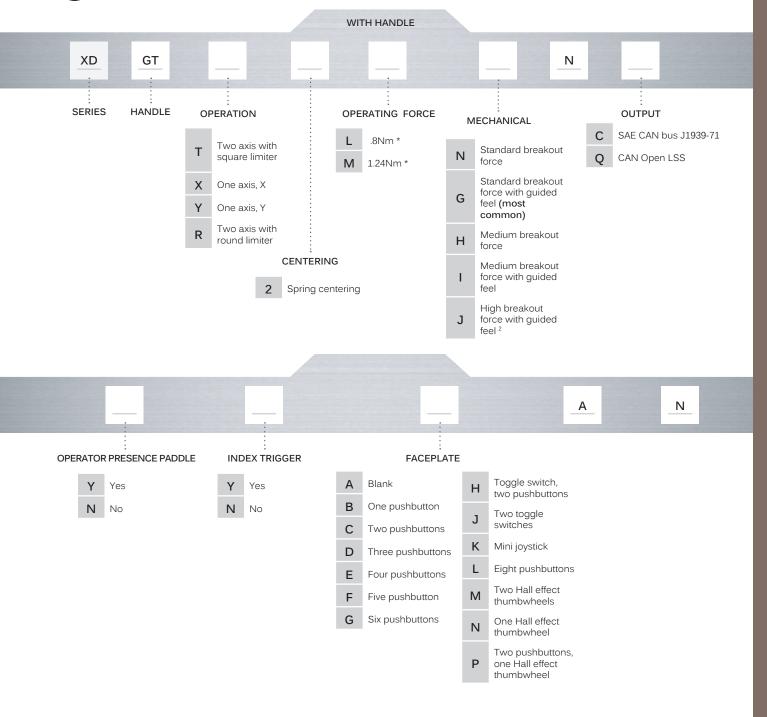
ERMEC BILBAO Tel. (+34) 946 455 054 bilbao@ermec.com

ERMEC PORTUGAL Tel. (+351) 707 509 539 portugal@ermec.com

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BUILD YOUR PART NUMBER



Notes

The Guided feel option aids the joystick lever into the cardinal direction Guided feel option is recommended for «Operating force Option M»

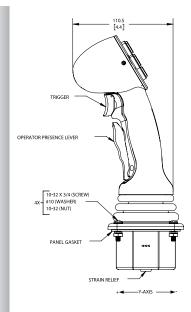
 $^{^{1}}$ Measured at $\pm 10^{\circ}$ (50% travel) from center (without guided feel.)

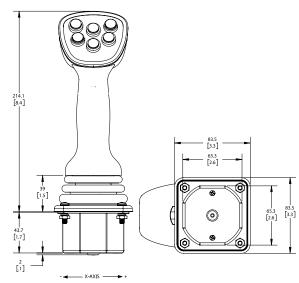
² High breakout force can only come with round limiter plate.

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DIMENSIONS









COMPONENT DESCRIPTIONS



- MT series: Sealed toggle switch
 - MOM-OFF-MOM



- IM series: Sealed momentary pushbutton
- Snap action
- Red



- TS series : Miniature Hall effect joystick
- Two axis, proportional output
- Castle actuator
- HR series: Hall effect thumbwheel
- One axis, proportional output
- Black wheel



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FACEPLATE OPTIONS





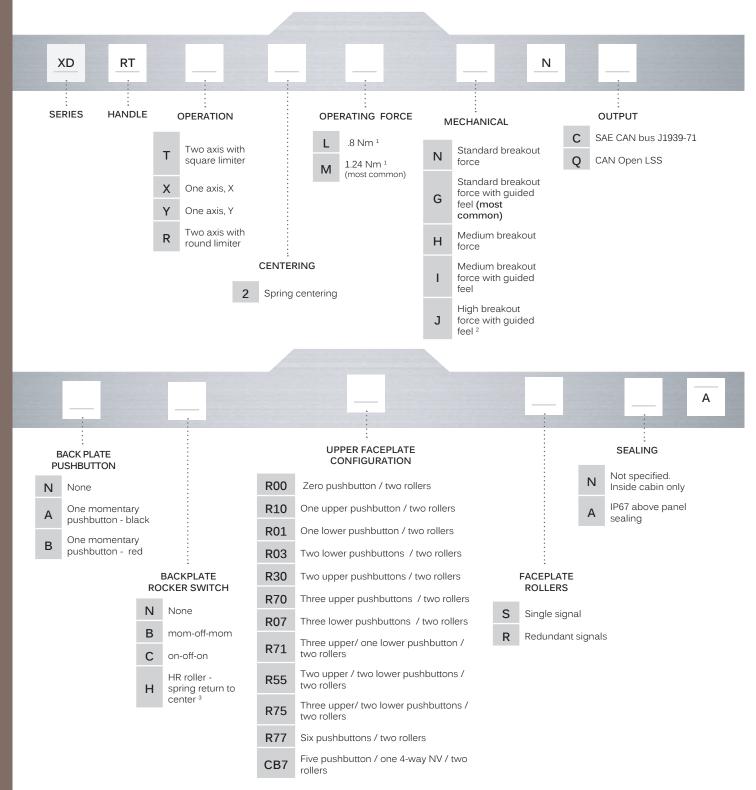
ERMEC, S.L. C/ Francesc Teixidó, 22 P. E. Granland, Badalona Sur 08918 Badalona Barcelona (SPAIN)

Tel. (+34) 902 450 160 Fax (+34) 902 433 088 ermec@ermec.com

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BUILD YOUR PART NUMBER

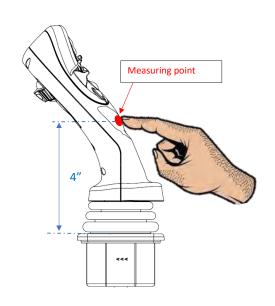


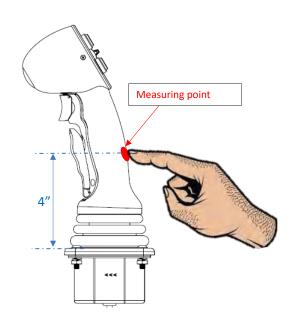
The Guided feel option aids the joystick lever into the cardinal direction Guided feel option is recommended for «Operating force Option M»

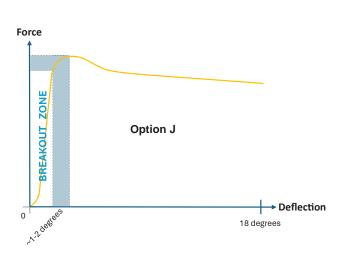
- ¹ Measured at ±10° (50% travel) from center (without guided feel.)
- ² High breakout force can only come with round limiter plate. ³ Joystick cannot be IP67 with HR roller on the black plate

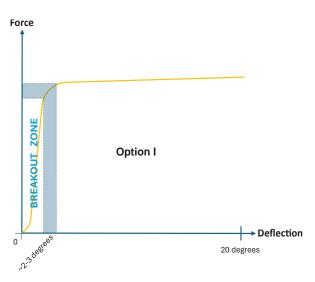
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ACTUATION FORCE









MEASUREMENT ON CARDINAL DIRECTION (in lbf)							
BREAKOUT 5% of deflection 50% of deflection 75% of deflection 100% of deflection							
" " (medium breakout force + guided feel)	0.8±0.3	1.2±0.2	1.3±0.2	1.32±0.15			
"J" (high breakout force + guided feel)	1±0.3	1.75±0.2	1.65±0.2	1.55±0.15			

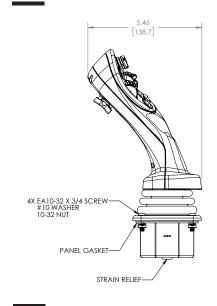
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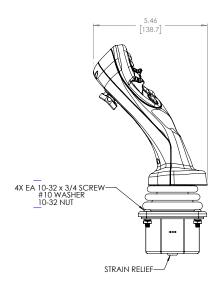
CONTOURED FACEPLATE

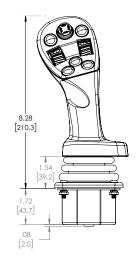


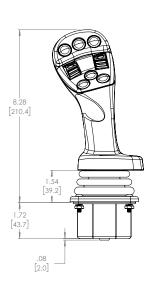
RAISED FACEPLATE











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COMPONENT DESCRIPTIONS

FACEPLATE



- IX series: Sealed momentary pushbutton
- Protective elastomer boot
- IP67 panel sealed
- Black



- HR series: Hall effect thumbwheel
- One axis, proportional control
- Single or redundant outputs
- Optional IP67 panel sealing
- Black



- NV series: 4 way navigation switch
- Tactical momentary actuation
- IP67 panel sealed

BACKPLATE



- IS series: Sealed momentary pushbutton
- Tactile feedback
- IP67 panel sealed
- Black



- One axis, proportional control
- Single output
- Black



- FNR series: Three position rocker switches
- MOM-OFF-MOM actuation
- IP69K panel sealed
- ON-ON-ON latch position



BACKPLATE OPTIONS



N no pushbutton N no rocker switch



N no pushbutton B mom-off-mom rocker switch

A black pushbutton N no rocker switch



A black pushbutton H roller spring return to center



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RAISED FACEPLATE OPTIONS







CONTOURED FACEPLATE OPTION



CB7



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C/ Francesc Teixidó, 22 P.E. Granland, Badalona Sur 08918 Badalona (Barcelona) SPAIN comercial@ermec.com

comercial@ermec.com Tel. (+34) 934 501 600 Fax (+34) 934 330 885 www.ermec.com

ERMEC MADRID Tel. (+34) 918 285 651 madrid@ermec.com

ERMEC BILBAO Tel. (+34) 946 455 054 bilbao@ermec.com

ERMEC PORTUGAL Tel. (+351) 707 509 539 portugal@ermec.com