

# XF series

Multi-axis rugged fingertip controllers •  
non-contacting Hall effect technology



## DISTINCTIVE FEATURES

- Rugged design for vehicle applications
- Up to three axis
- CAN bus J1939 & CANopen protocol options
- USB protocol options
- Panel sealed up to IP67



## ENVIRONMENTAL SPECIFICATIONS

- Operating Temperature: -40°C to +85°C (-40°F to 185°F)
- Storage Temperature: -40°C to +85°C (-40°F to 185°F)
- Above Panel Sealing: Up to IP67 (subject to final specifications)
- EMC Immunity Level (V/M): EN61000-4-3
- EMC Emissions Level: EN61000-6-3:2001
- ESD: EN61000-4-2
- Output linearity:  $\pm 200\text{mV}$
- Dual output interlinearity (X/Y):  $\pm 400\text{mV}$
- Dual output interlinearity (Z):  $\pm 600\text{mV}$



## SENSOR SPECIFICATIONS

- Sensor: Hall effect, single or dual
- Supply Voltage Range: 5VDC  $\pm 0.01\text{VDC}$
- Supply Current: 15mA, +10mA per axis (single sensor)
- Reverse Polarity Max: -10VDC
- Transient Overvoltage Max: 16VDC
- Ratiometric Output Voltage: see output options
- Output Impedance: 2 $\Omega$



The company reserves the right to change specifications without notice.



**ERMEC, S.L. BARCELONA**  
C/ Francisc Teixidó, 22  
08918 Badalona SPAIN

Tel. +34 902 450 160  
info@ermec.com  
www.ermec.com

**ERMEC, S.L. - MADRID**  
C/ Puerto Rico, 4  
28222 Majadahonda (Madrid) SPAIN

bilbao@ermec.com  
portugal@ermec.com

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## MECHANICAL SPECIFICATIONS (X/Y AXIS)

- Break Out Force: 1.3N (0.3lbf)
- Operating Force: 2.8N (0.63lbf)
- Maximum Applied Force: 350N (78.00lbf)
- Deflection Angle: 36° (±18° from center)
- Expected Mechanical Life: 5 million lifecycles
- Lever Action: Single spring, omnidirectional



## MECHANICAL SPECIFICATIONS (Z AXIS)

- Break Out Torque: 0.09Nm (0.80lbf in)
- Operating Torque: 0.121Nm (1.07lbf in)
- Maximum Allowable Torque: 9.0Nm (80lbf in)
- Degrees of rotation: 60° (30° from center)
- Expected Mechanical Life: 5 million lifecycles
- Handle Action: Spring centering



## MATERIALS

- Shaft: Stainless Steel
- Boot: Silicone
- Handles: Glass filled nylon\*
- Body: Glass filled nylon

## TERMINATION

### NOTES

The XF series (Output options: AA – HH) is configured with a Hirose DF11-12DP-2DS9(24) connector (male receptacle)(Fig 1).

The mating cable is not included but may be selected from the configuration guide.

The mating cable features a Hirose DF11-12DS-2C (female socket)(Fig 2).

Connector specifications: 12 position, 2mm pitch dual row (2x6) pin header.

Wire Color	Description
Black	Ground
Red	Power
Blue/White	X-Axis (Dual Output)
Blue	X-Axis
Yellow/Black	Y-Axis (Dual Output)
Yellow	Y-Axis
Green/Black	Z-Axis (Dual Output)
Green	Z-Axis
Orange	Button 1
White	Button Common
Violet	Button 2



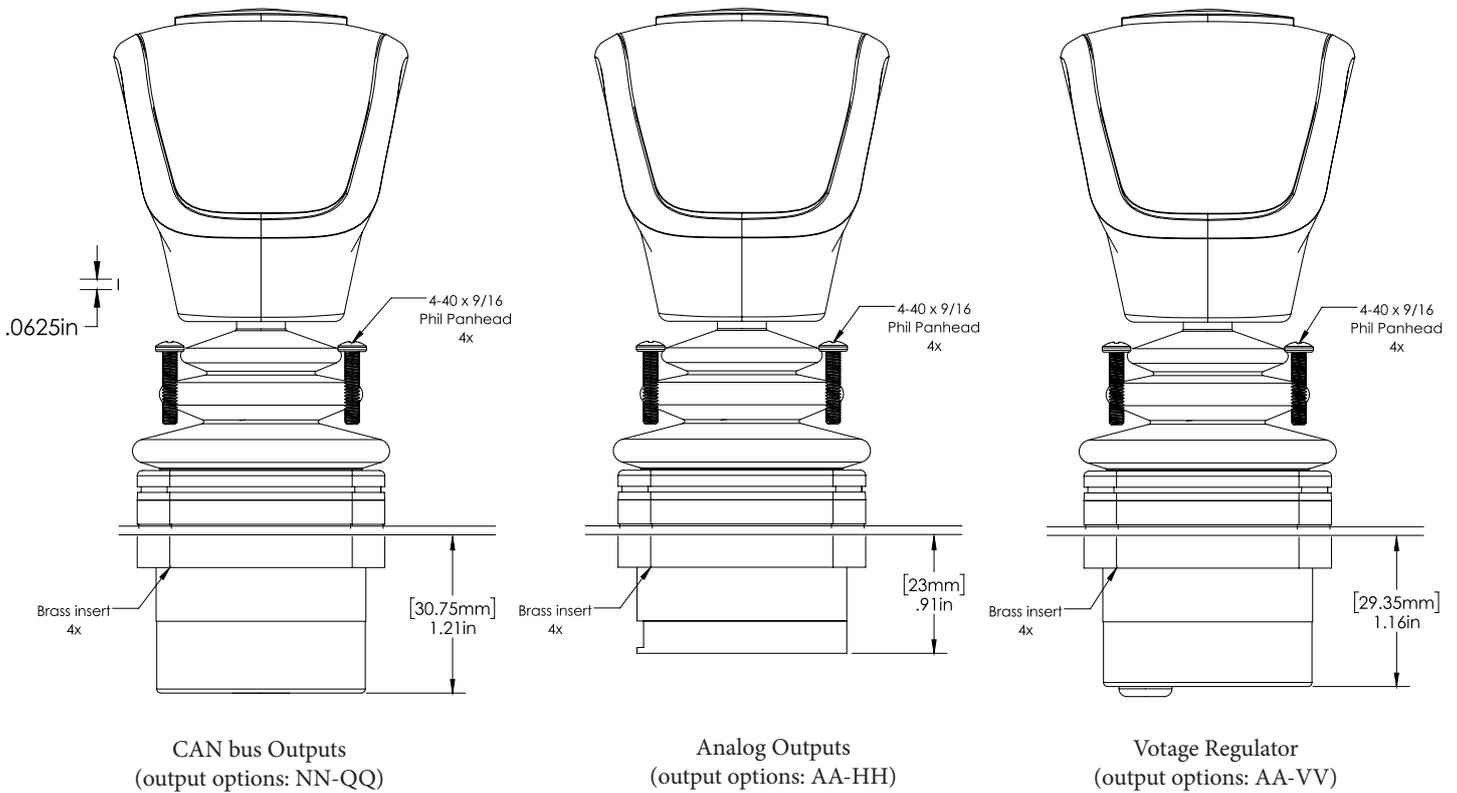
Fig 1F



ig 2

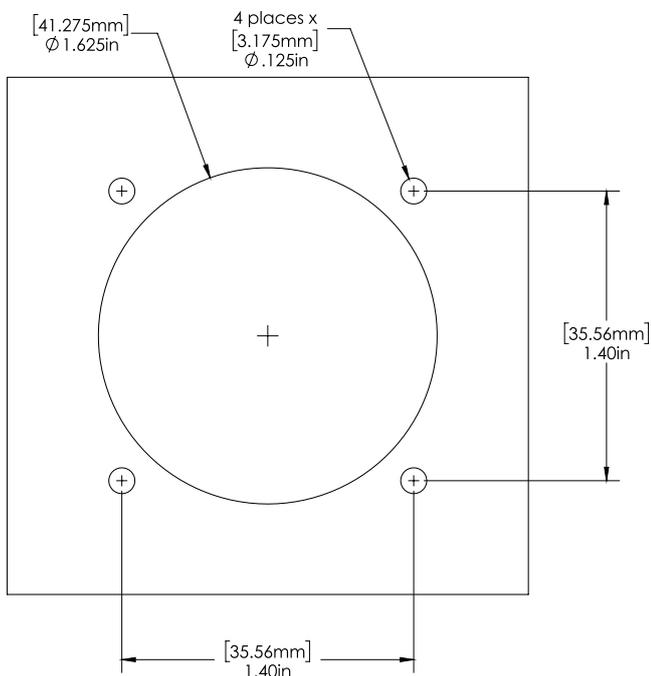
\* Most handles, dependent upon configurations

## GENERAL MOUNTING DIMENSIONS & SUGGESTED PANEL OPENING

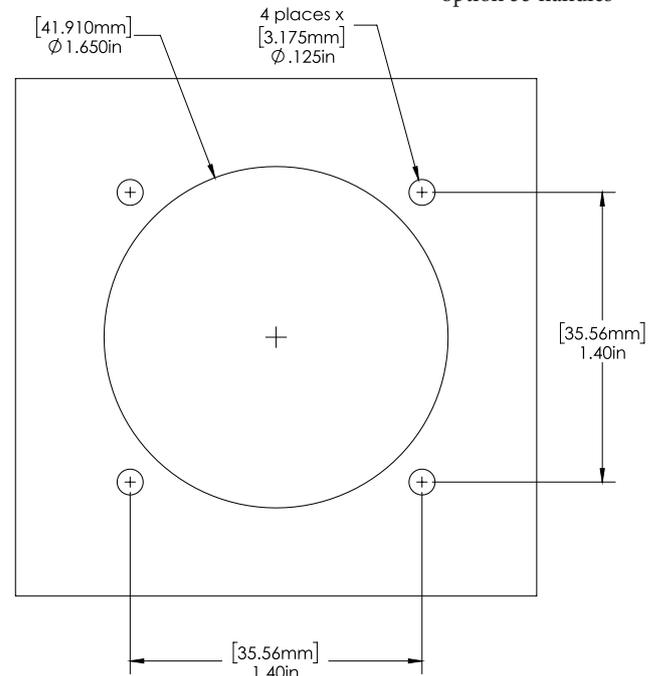


## PANEL CUT-OUT

### DROP-IN MOUNT



### REAR MOUNT



Not available for option 55 handles

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## CAN J1939 INTERFACE SPECIFICATION

The XF Series joystick can be configured with a maximum of three axis and two buttons. All axis and button data are delivered on a CAN 2.0B compliant physical interface. Two additional signals allow configuration of the controller Source Address. Controller messages are delivered per the SAE J1939-71 message protocol.

### CAN 2.0B INTERFACE PARAMETERS

- Baud rate: 250 KHz
- Transmission repetition rate: 50ms
- BJMI/EJMI interval time: 20ms
- Terminating resistor: No (available by special request to factory)
- Standard 22 AWD harness 45cm
- Optional connection to Deutsch DTM04-6P connector

Pin	Color	Function
1	White	CAN Lo
2	Green	CAN Hi
3	Blue	ID Selection LSB
4	Orange	ID Selection MSB
5	Black	Ground
6	Red	7-35VDC

### CAN MESSAGE PROTOCOL

- Primary Axis and button data on Basic Joystick Message 1 (BJM1):
  - Priority: 3
  - Base PGN: 0xFDD6
  - Source address: 0x16<sup>1</sup>
  - Data field: 8 bytes
- Redundant Axis data on Extended Joystick Message 1 (EJMI):
  - Priority: 3
  - Base PGN: 0xFDD7
  - Source address: 0x16<sup>1</sup>
  - Data field: 8 bytes

Note 1: Alternate source addresses can be configured by grounding of the blue and/or orange wires.

- Source address= 0x16: ORANGE= floating, BLUE= floating (default)
- Source address= 0x26: ORANGE= floating, BLUE= grounded
- Source address= 0x36: ORANGE= grounded, BLUE= floating
- Source address= 0x46: ORANGE= grounded, BLUE= grounded

### BJM1 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	Primary X-axis neutral position status
1/3	2	Primary X-axis left position status
1/5	2	Primary X-axis right position status
1/7 to 2/8	10	Primary X-axis position data
3/1	2	Primary Y-axis neutral position status
3/3	2	Primary Y-axis down position status
3/5	2	Primary Y-axis up position status
3/7 to 4/8	10	Primary Y-axis position data
6/5	2	Button 2 status
6/7	2	Button 1 status

### EJM1 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	Redundant X-axis neutral position status
1/3	2	Redundant X-axis left position status
1/5	2	Redundant X-axis right position status
1/7 to 2/8	10	Redundant X-axis position data
3/1	2	Redundant Y-axis neutral position status
3/3	2	Redundant Y-axis down position status
3/5	2	Redundant Y-axis up position status
3/7 to 4/8	10	Redundant Y-axis position data
5/1	2	Primary Z-axis neutral position status
5/3	2	Primary Z-axis counter-clockwise position status
5/5	2	Primary Z-axis clockwise position status
5/7 TO 4/8	10	Primary Z-axis position data

### CUSTOM CAN BUS J1939 FIRMWARE\*

- Baud rate: 125 kbps, 500kbps, 1Mbps (250 KHz default)
- Custom CAN addresses
- Custom CAN bus output

\* Custom CAN bus firmware available upon request.

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## CANOPEN INTERFACE SPECIFICATION

### CANOPEN INTERFACE PARAMETERS

- Baud rate: 250 bps
- Node ID: 20h
- Buttons: 1A0H (180H + NODE ID)
- Analog (axis) outputs: 2A0h (280h + Node ID)
- Heartbeat (500ms): 720h (700h + Node ID)
- Axis resolution: 8 bit
- Network Management: Auto start enabled
- Standard 22 AWG harness 45cm
- Optional Deutsch DTM04-6P connector:

### AWG22 WIRE CABLE HARNESS

Color	Signal
Red	Supply Power (7VDC to 35VDC)
Black	Ground
Green	CAN high data
White	CAN low data
Blue	Node ID Selection (LSB)
Orange	Node ID Selection (MSB)

### DEUTSCH 6 PIN OPTIONAL

Pin	Color	Signal
1	Red	Supply Power (7VDC to 35VDC)
2	Black	Ground
3	Green	CAN high data
4	White	CAN low data
5	Blue	Node ID Selection (LSB)
6	Orange	Node ID Selection (MSB)

### BUTTON OUTPUT CONFIGURATION

Buttons status is transmitted in the 1-byte data field of frames with an identifier of 1A0 (default)

Identifier	Byte 0
1A0	[7:0]

### ANALOG OUTPUT CONFIGURATION

8-bit analog data is transmitted in the 3-byte data field of frames with an identifier of 2A0 (default)

Identifier	Byte 0	Byte 1	Byte 2
2A0	A_IN0 [7:0]	A_IN1 [7:0]	A_IN2 [7:0]

### SELECTABLE NODE ID

#	Blue wire	Orange wire	Node ID
1	OPEN	OPEN	20H
2	GND	OPEN	21H
3	OPEN	GND	22H
4	GND	GND	23H

### CUSTOM CANOPEN FIRMWARE\*

- Baud rate: 125 kbps, 500kbps, 1Mbps (250 bps default)
- Custom Node IDs (default 20 hexadecimal)
- 10-bit axis resolution
- 12-bit axis resolution
- Signed resolution

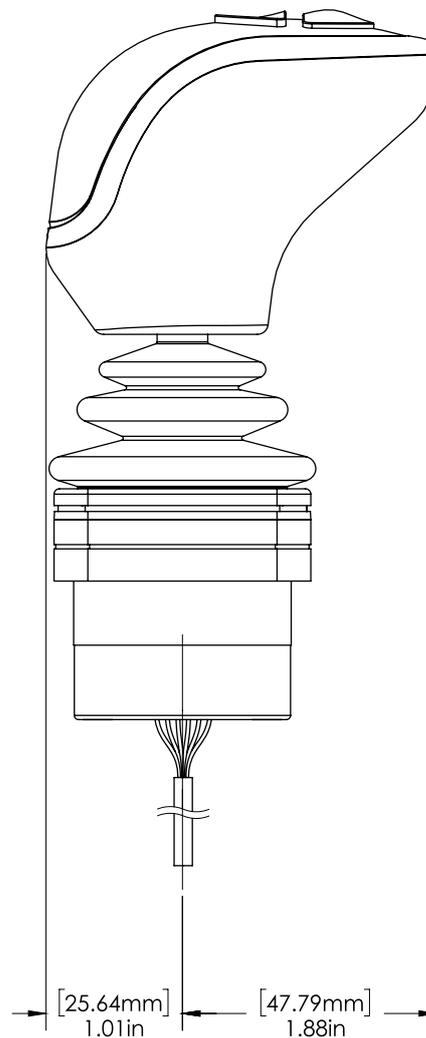
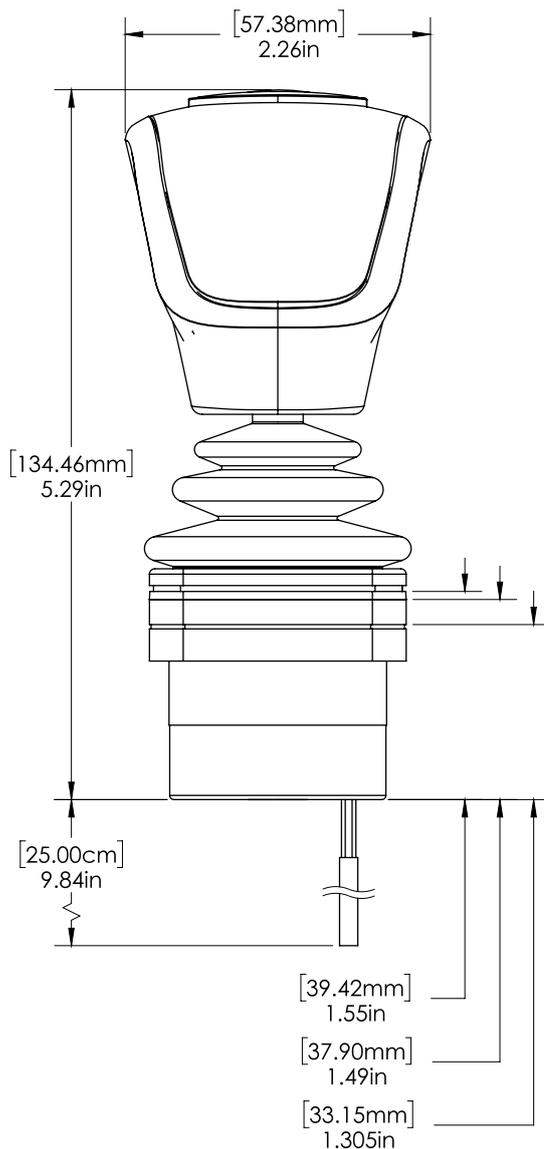
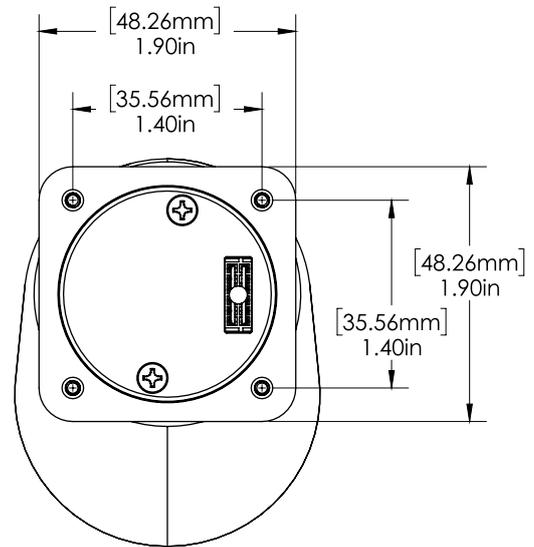
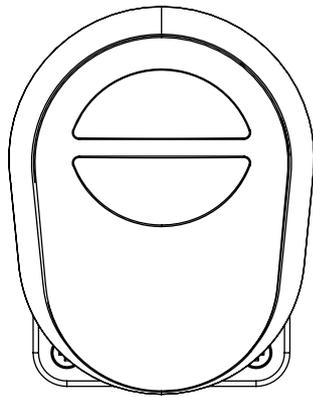
\* Custom CAN bus firmware available upon request.

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## CAN BUS SPECIFICATIONS: DIMENSIONS





## VOLTAGE REGULATOR SPECIFICATIONS

The Voltage Regulator allows APEM's Hall effect joysticks to operate with a range of supply voltages..

### Voltage Regulator - Unipolar

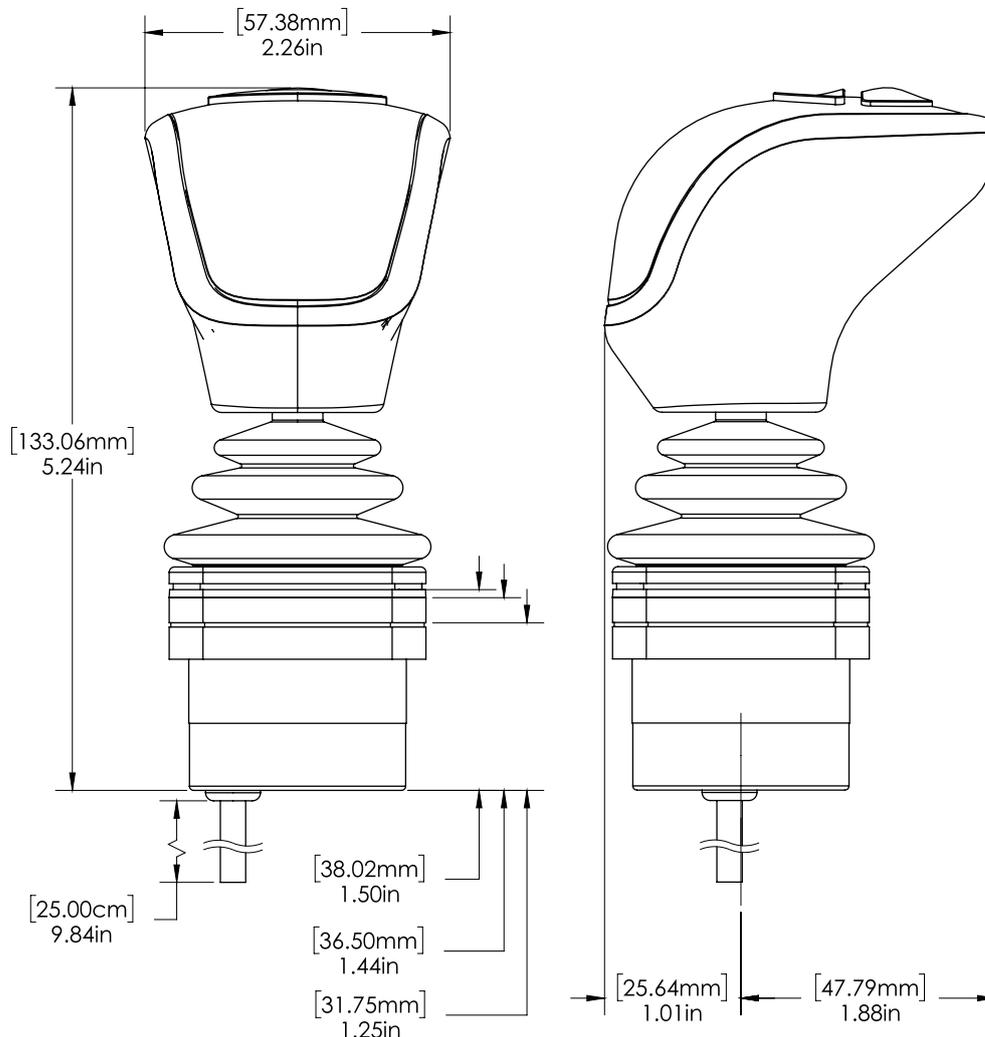
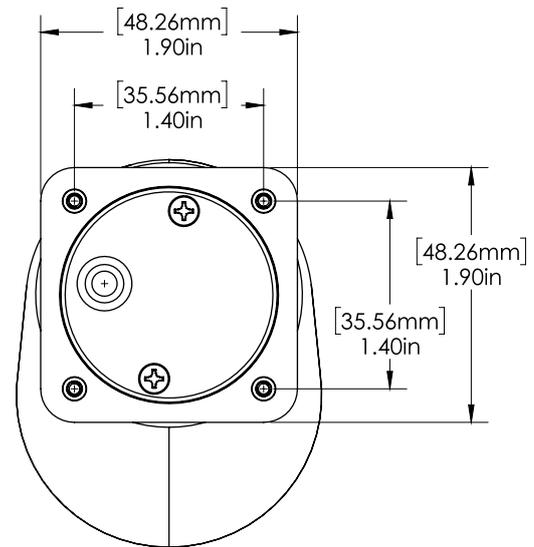
- Supply Voltage Range: 8-35VDC
- Output Voltage Range: see output options
- Maximum Current: 90mA

### Voltage Regulator - Bipolar

- Supply Voltage Range: 11-35VDC
- Output Voltage Range:  $\pm 10$ VDC
- Maximum Current: 90mA

### Termination (supplied cable)

- 28 AWG 16.5cm  $\pm 1.25$ cm PTFE



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## USB SPECIFICATION

- Supply Voltage Range: 5.00VDC
- Maximum current: 70mA
- USB version: 2.0

### USB GAME CONTROLLER

Featuring USB 2.0 HID compliant interface, APEM's USB joysticks are recognized as standard HID "game controller" devices. Adhering to the HID specification, APEM's USB joysticks are plug-and-play with most versions of Windows. Joystick button and axis assignments are dependent upon the controlled application.

#### Features

- USB 2.0 HID compliant "game controller" device
- Easy to install and operate
- Functions determined by controlled application
- 12-bit (0 to 4095) axis resolution

#### Termination (supplied cable)

- USB Male Type A Connector (198cm)

### USB CURSOR EMULATION

The Cursor Emulation option converts multi-axis joystick output into a mouse or cursor control device. The Cursor Emulation option is ideal for vehicle applications subjected to dirt and high vibration which makes operating a traditional cursor control device difficult.

#### Features

- HID compliant "mouse" device

#### Button Function

- B1: Left Mouse Click
- B2: Right Mouse Click

#### Termination (supplied cable)

- USB Male Type A Connector (198cm)

### SUPPORTED OPERATING SYSTEMS: USB GAME CONTROLLER AND CURSOR EMULATION

#### Windows Operating System

- Windows 7
- Windows 8.1
- Windows 10

#### Linux Operating System

APEM's USB joysticks are compatible with Linux, although system compatibility is not guaranteed. The user is responsible for verifying specific Linux OS compatibility.

#### Custom Firmware

Custom configurations and firmware is available upon request. Available options include:

- 8-bit axis resolution
- 10-bit axis resolution
- Signed bit axis resolution
- Custom USB product name

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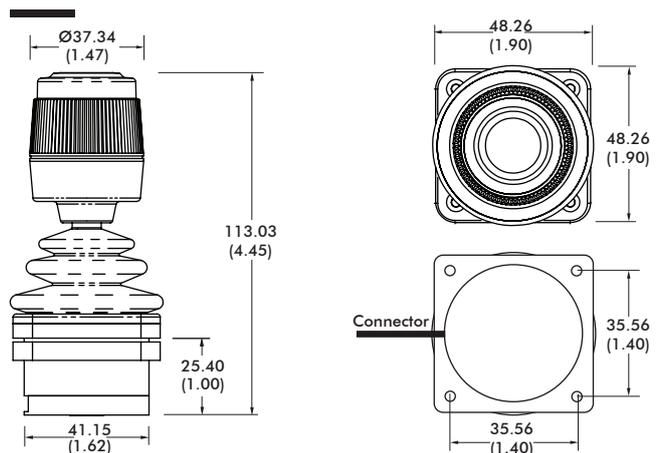
## BUILD YOUR PART NUMBER

XF		A	N							N			A		
SERIES	HANDLE	HANDLE ROTATAION		CENTERING			MECHANICAL FEATURES			SEALING		SPECIAL OPTIONS			
50	Three axis No buttons	N	Locked Z axis	S	Spring Centering			N	None			E	IP67 as standard		
		Z	Third axis Z active										V		
		OPERATION			OPERATING TORQUE			OUTPUT			TERMINATION				
		T	Two axis		A	(900-825)		AA	0V-5V		A	None			
		X	One axis (X only)		B	(900-1128)		BB	0.5V-4.75V		B	Mating cable without connector (output AA-HH) *			
		Y	One axis (Y only)					CC	0.5V-4.5V						
								DD	1V-4V						
								EE	(0V-5V)(5V-0V)						
								FF	(0.25V - 4.75V) (4.75V - 0.25V)						
								GG	(0.5V - 4.5V) (4.5V - 0.5V)						
								HH	(1V - 4V) (4V - 1V)						
								VV	±10V						
								NN	CAN bus J1939-71						
								PP	CANopen						
								QQ	CANopen LSS						
								UU	USB joystick, Game Controller						
								TT	USB mouse, Cursor Control						

1 Available for output options AA-HH

\* Cable is supplied for output output NN-TT

## DIMENSIONS



ERMEC, S.L. BARCELONA  
C/ Francisc Teixidó, 22  
08918 Badalona SPAIN

Tel. +34 902 450 160  
info@ermec.com  
www.ermec.com

ERMEC, S.L. - MADRID  
C/ Puerto Rico, 4  
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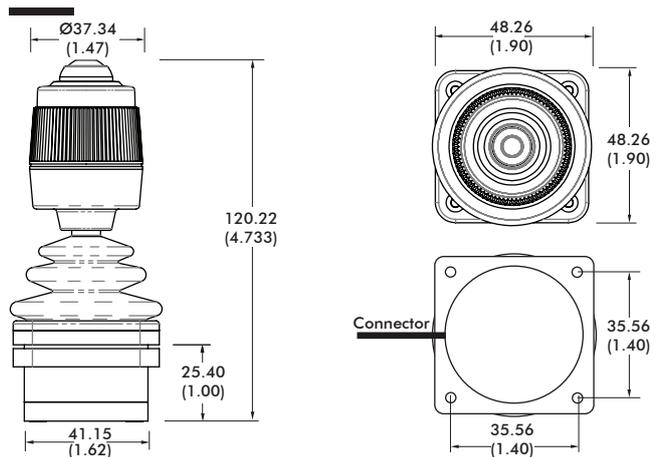
## BUILD YOUR PART NUMBER

XF		A	N						N			A						
SERIES	HANDLE	HANDLE ROTATAION		CENTERING			MECHANICAL FEATURES			SEALING		SPECIAL OPTIONS						
51	Three axis One button	N	Locked Z axis	S	Spring Centering			N	None			E	IP67 as standard	V	Voltage Regulator <sup>1</sup>			
				OPERATION			OPERATING TORQUE			OUTPUT		TERMINATION						
				T	Two axis			A	(900-825)			AA	0V-5V		A	None		
				X	One axis (X only)			B	(900-1128)			BB	0.5V-4.75V		B	Mating cable without connector *		
				Y	One axis (Y only)						CC	0.5V-4.5V						
										DD	1V-4V							
										EE	(0V-5V)(5V-0V)							
										FF	(0.25V - 4.75V) (4.75V - 0.25V)							
										GG	(0.5V - 4.5V) (4.5V - 0.5V)							
										HH	(1V - 4V) (4V - 1V)							
										VV	±10V							
										NN	CAN bus J1939-71							
										PP	CANopen							
										QQ	CANopen LSS							
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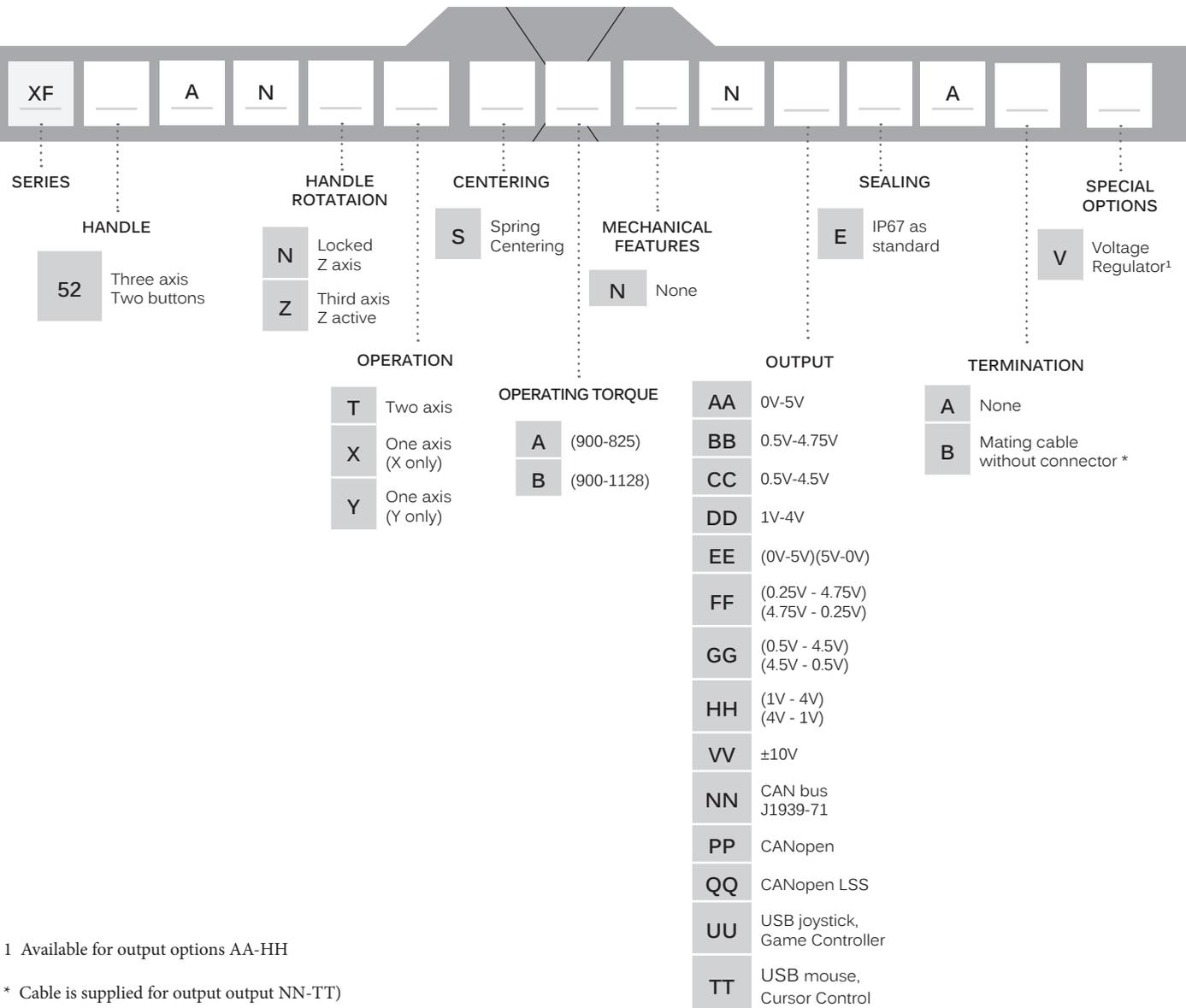
## DIMENSIONS



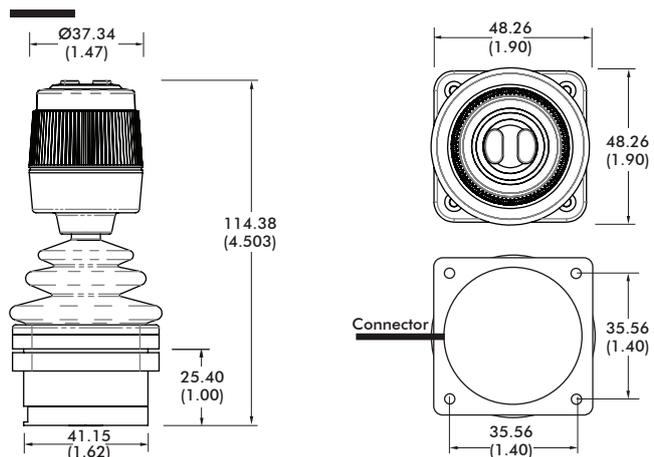
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## BUILD YOUR PART NUMBER



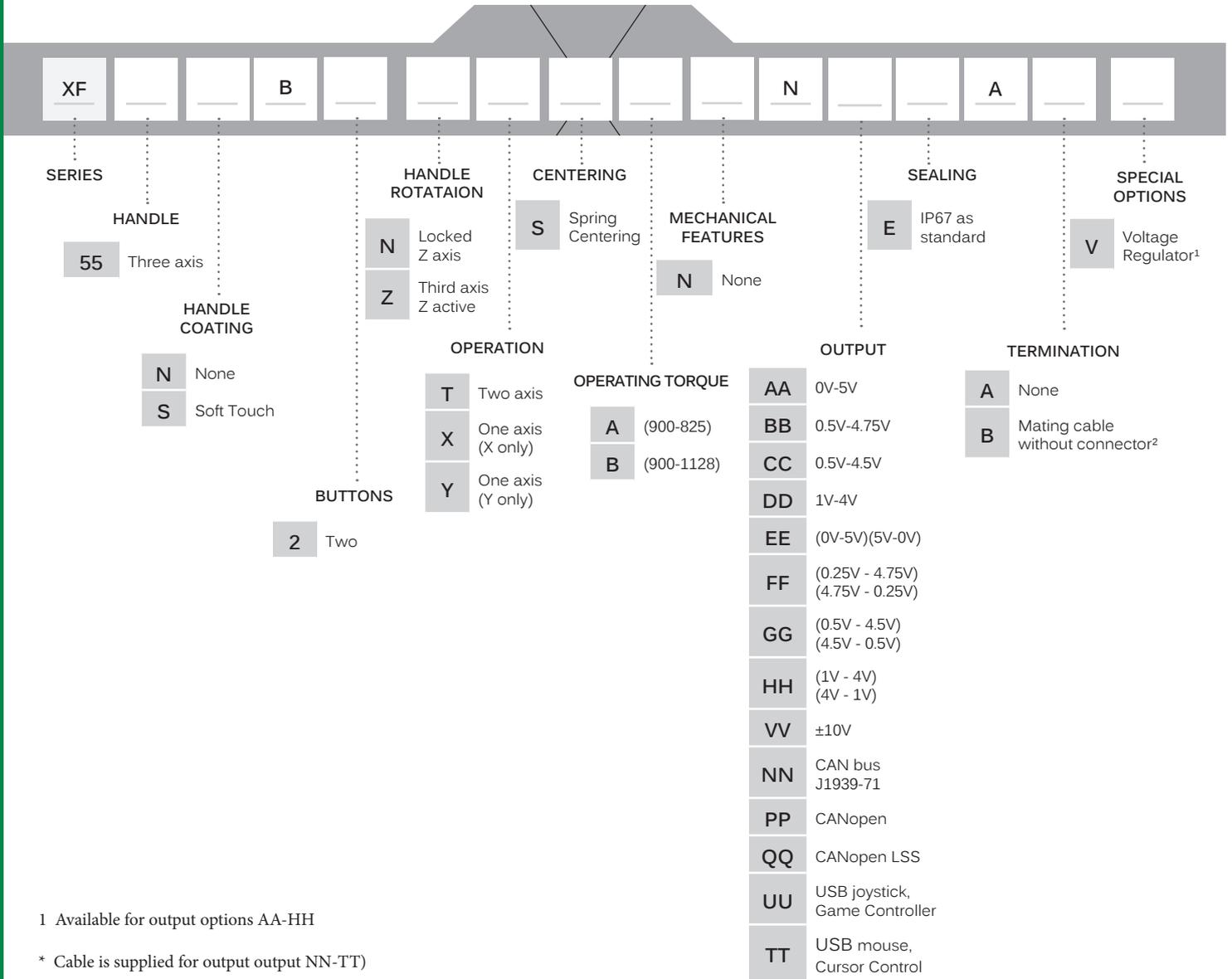
## DIMENSIONS



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## BUILD YOUR PART NUMBER



**SERIES**  
XF

**HANDLE**  
55 Three axis

**HANDLE COATING**  
N None  
S Soft Touch

**HANDLE ROTATION**  
N Locked Z axis  
Z Third axis Z active

**BUTTONS**  
2 Two

**OPERATION**  
T Two axis  
X One axis (X only)  
Y One axis (Y only)

**CENTERING**  
S Spring Centering

**MECHANICAL FEATURES**  
N None

**OPERATING TORQUE**  
A (900-825)  
B (900-1128)

**SEALING**  
E IP67 as standard

**OUTPUT**  
AA 0V-5V  
BB 0.5V-4.75V  
CC 0.5V-4.5V  
DD 1V-4V  
EE (0V-5V)(5V-0V)  
FF (0.25V - 4.75V) (4.75V - 0.25V)  
GG (0.5V - 4.5V) (4.5V - 0.5V)  
HH (1V - 4V) (4V - 1V)  
VV ±10V  
NN CAN bus J1939-71  
PP CANopen  
QQ CANopen LSS  
UU USB joystick, Game Controller  
TT USB mouse, Cursor Control

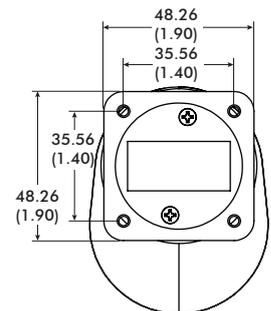
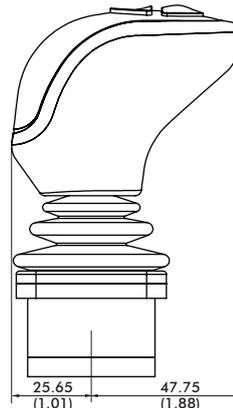
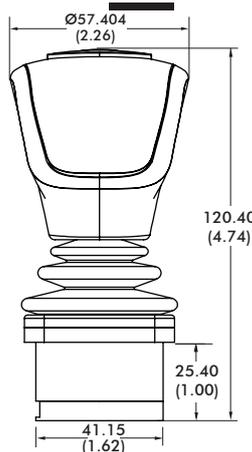
**SPECIAL OPTIONS**  
V Voltage Regulator<sup>1</sup>

**TERMINATION**  
A None  
B Mating cable without connector<sup>2</sup>

<sup>1</sup> Available for output options AA-HH

\* Cable is supplied for output output NN-TT)

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